

Critical intermittency in random interval maps

Workshop on affine and overlapping IFSs

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Good maps and bad maps

Homburg, Kalle, Ruziboev, Verbitskiy, Z. (2021):

We consider two types of maps, **good maps** and **bad maps**.

The class of **good maps** consists of maps

$$T_g : [0, 1] \rightarrow [0, 1], \quad T_g(x) = 1 - |1 - 2x|^{r_g},$$

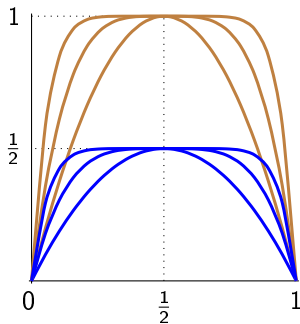
where $r_g \geq 1$.

The class of **bad maps** consists of maps

$$T_b : [0, 1] \rightarrow [0, 1], \quad T_b(x) = \frac{1}{2} - \frac{1}{2} |1 - 2x|^{\ell_b},$$

where $\ell_b > 1$, called the *critical order*.

Ex: $r_g = 2, \ell_b = 2$ give $T_g(x) = 4x(1 - x)$, $T_b(x) = 2x(1 - x)$.

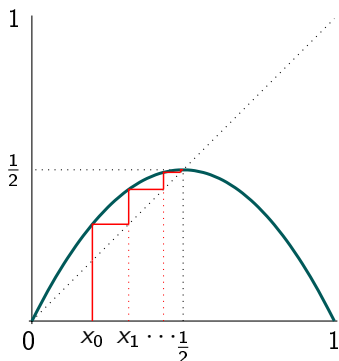


Dynamics under bad maps

The orbits under a bad map T_b are of the form $\{x_n\}_{n=0}^{\infty}$ where $x_0 \in [0, 1]$ and, for each $n \in \mathbb{N}$,

$$\begin{aligned}x_n &= T_b(x_{n-1}) = \cdots = T_b^n(x_0) \\ &= \frac{1}{2} - \frac{1}{2}|1 - 2x_0|^{\ell_b^n}.\end{aligned}$$

Hence, each bad map has $\frac{1}{2}$ as **superattracting fixed point** with $(0, 1)$ as basin of attraction.



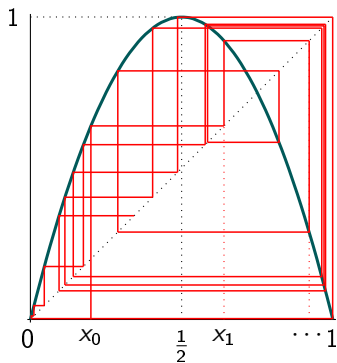
Dynamics under good maps

The following result is a special case of the Main Theorem in Nowicki, van Strien (1991).

Theorem

Let T_g be a good map.

1. There exists a unique T_g -invariant, T_g -ergodic probability measure μ_g such that $\mu_g \ll \text{Leb}$, where Leb is the Lebesgue measure on $[0, 1]$.
2. The density $\frac{d\mu_g}{d\text{Leb}}$ is bounded away from zero, is locally Lipschitz on $(0, 1)$ and is in L^q if and only if $q \in [1, \frac{r_g}{r_g-1})$.



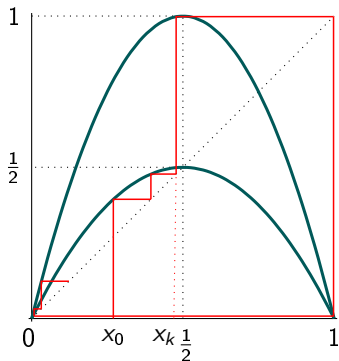
Critical intermittency

Let T_1, \dots, T_N be a finite collection of good and bad maps, containing at least one of either type. Let $(p_j)_{j=1}^N$ be a prob. vector. Let $x_0 \in [0, 1]$ and for each $n \in \mathbb{N}$, independently,

$$x_n = \begin{cases} T_1(x_{n-1}), & \text{with probability } p_1, \\ \vdots & \vdots \\ T_N(x_{n-1}), & \text{with probability } p_N, \end{cases}$$

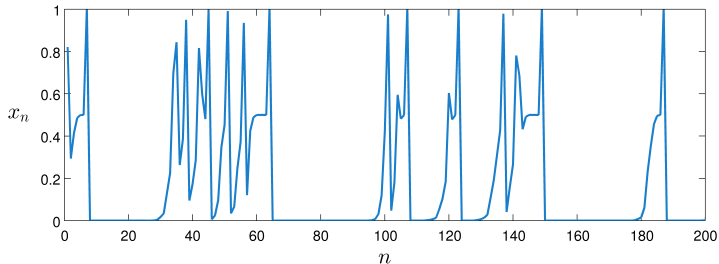
The typical behaviour is the following:

- ▶ The orbit **converges superexp. fast** to $\frac{1}{2}$ under applications of bad maps up to some time k ,
- ▶ At time $k + 1$, the orbit is mapped close to 1 by a good map,
- ▶ Then the orbit is mapped close to 0 and **diverges exp. fast from 0** under applications of either good or bad maps.



Critical intermittency

Time series of the random model consisting of the logistic maps $T_4(x) = 4x(1 - x)$ and $T_2(x) = 2x(1 - x)$, both chosen with equal probability at each timestep.



Abbasi, Gharaei, Homburg (2018): Random interval map composed of T_4 and T_2 admits a σ -finite acs measure μ . Furthermore, μ is infinite in case $p_2 > \frac{1}{2}$, i.e. choosing T_2 with higher probability.

Phase transition

Let T_1, \dots, T_N be a finite collection of good and bad maps, containing at least one of either type. Let $(p_j)_{j=1}^N$ be a prob. vector. A Borel measure μ on $[0, 1]$ is *stationary* if

$$\sum_{j=1}^N p_j \mu(T_j^{-1}A) = \mu(A), \quad \forall A \subseteq [0, 1] \text{ Borel.}$$

Theorem (Homburg, Kalle, Ruziboev, Verbitskiy, Z. (2021))

1. *There exists a unique (up to scalar multiplication) σ -finite stationary measure μ such that $\mu \ll \text{Leb}$.*
2. *The density $\frac{d\mu}{d\text{Leb}}$ is bounded away from zero, is locally Lipschitz on $(0, \frac{1}{2}) \cup (\frac{1}{2}, 1)$ and is not in L^q for any $q > 1$.*
3. *Set $\Sigma_B = \{1 \leq j \leq N : T_j \text{ bad map}\}$ and $\theta = \sum_{b \in \Sigma_B} p_b \ell_b$. Then μ_p is finite if and only if $\theta < 1$.*

Hence, the random system exhibits a **phase transition at $\theta = 1$** .